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Differential Form of Gauss's Law Thus $\frac{D_{x}(x+\Delta x,y,z)-D(x,y,z)}{\Delta x}+\frac{D_{y}(x,y+\Delta y,z)}{-D_{y}(x,y,z)}$ Δy →0 ΔZ →0 $+ D_{z} (x, y, z+\Delta z) - D_{z}(x, y, z) = \rho_{v}(x, y, z)$ $\rho_{v}(x,y,z) = \frac{\partial D_{x}(x,y,z)}{\partial x} + \frac{\partial D_{y}(x,y,z)}{\partial y} + \frac{\partial D_{z}(x,y,z)}{\partial z}$ $= \nabla \cdot \overrightarrow{D}(x, y, Z)$ Georgia Tech Emag copyright 2009 - all rights reserved



Recall
$$\nabla = \frac{1}{2x} \hat{x} + \frac{1}{2} \hat{y} + \frac{1}{2} \hat{z}$$

Del operator Shorthand notation

 $\nabla \cdot \vec{D} = \rho_v - Gauss's Law in Differential or "Point" Form

- One of Maxwell's equations

Divergence = "Sourciness"$

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The Divergence Theorem

Basic Relationship in Vector Calculus $\vec{p} \cdot \vec{D} \cdot d\hat{n}' = \int p_v dv' = \int \vec{r} \cdot \vec{D} dv'$

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Divergence in Non-Cartesian Coordinates

Keep in mind, V.D defined differently in spherical and cylindrical coords:

cyl:
$$\nabla \cdot \vec{D} = \frac{1}{\rho} \frac{\lambda}{\partial \rho} (\rho D_{\rho}) + \frac{1}{\rho} \frac{\partial D_{\sigma}}{\partial \phi} + \frac{\partial D_{z}}{\partial z}$$

sph:
$$\nabla \cdot \vec{D} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \Omega_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (D_{\theta} \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (D_{\theta} \sin \theta)$$

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